

SIMULTANEOUS RECONSTRUCTION OF PHASE VELOCITY AND DISSIPATION  
COEFFICIENT IN A STRATIFIED HALF-SPACE USING 3-D REFLECTIVITY

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Consider the following hyperbolic equation

$$\frac{1}{c(z)^2} \frac{\partial^2}{\partial t^2} u - \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) u + b(z) \frac{\partial}{\partial t} u = 0, \quad (x, y, z) \in \mathcal{R}^3, \quad (1)$$

in a stratified half-space  $z > 0$  where the parameters  $c(z)$  (phase velocity) and  $b(z)$  (dissipation coefficient) vary with the depth  $z$ . The sources, with compact spatial support, are located in the upper half-space  $z < 0$  which is homogeneous and non-dissipative. We assume that the incident fields will not reach the surface  $z = 0$  until the time  $t = 0$ , i.e., we have the initial conditions

$$u(x, y, z, 0) = 0, \quad u_t(x, y, z, 0) = 0, \quad \text{for } z > 0. \quad (2)$$

In the inverse problem, we assume that only reflection data in the upper homogeneous half-space are measurable and we wish to achieve a simultaneous reconstruction of the phase velocity  $c(z)$  and the dissipation coefficient  $b(z)$ .

The present inverse approach is based upon the concept of wave splitting, which is associated with the factorization of wave equation [1]–[5]. Wave splitting refers to the decomposition of the total wave into up- and down-going waves with respect to parallel planes in the inhomogeneous medium. Thus, we introduce the following wave splitting

$$u^\pm = (1/2)[u \mp \mathcal{K}u_z], \quad (3)$$

where  $\mathcal{K}$  and its inverse  $\mathcal{K}^{-1}$  satisfy

$$\mathcal{K}^{-1} = \left( \frac{1}{c(z)^2} \frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2} - \frac{\partial^2}{\partial y^2} \right) \mathcal{K}. \quad (4)$$

The explicit form of the splitting operator  $\mathcal{K}$  is given by [4]

$$\mathcal{K}f(x, y, z, t) = \frac{1}{2\pi} \int_{\mathcal{R}^2} \frac{1}{r} f(x', y', z, \tau) H(\tau) dx' dy', \quad (5)$$

where  $r = \sqrt{(x - x')^2 + (y - y')^2}$ ,  $\tau = t - \frac{r}{c(z)}$  and  $H(t)$  is the Heaviside step function.

In the present paper, we use the transverse zeroth and second moments of the fields to reduce the three-dimensional problem to a set of one-dimensional problems. The transverse zeroth and second moments of the field  $u(x, y, z, t)$  are defined by

$$u_0(z, t) = \int \int_{\mathcal{R}^2} u(x, y, z, t) dx dy, \quad (6)$$

$$u_2(z, t) = \int \int_{\mathcal{R}^2} (x^2 + y^2)u(x, y, z, t) dx dy, \quad (7)$$

respectively. Taking zeroth and second moments of Eq. (3), we obtain the split moments

$$\begin{bmatrix} u_0^+ \\ u_0^- \\ u_2^+ \\ u_2^- \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2}c(z)\partial_t^{-1} & 0 & 0 \\ \frac{1}{2} & \frac{1}{2}c(z)\partial_t^{-1} & 0 & 0 \\ 0 & -c^3\partial_t^{-3} & \frac{1}{2} & -\frac{1}{2}c(z)\partial_t^{-1} \\ 0 & c^3\partial_t^{-3} & \frac{1}{2} & \frac{1}{2}c(z)\partial_t^{-1} \end{bmatrix} \begin{bmatrix} u_0 \\ u_{0z} \\ u_2 \\ u_{2z} \end{bmatrix} \equiv T \begin{bmatrix} u_0 \\ u_{0z} \\ u_2 \\ u_{2z} \end{bmatrix} \quad (8)$$

(note that  $u_0 = u_0^+ + u_0^-$  and  $u_2 = u_2^+ + u_2^-$ ), where the usual notation  $\partial_t^{-1}$  for the time integral has been adopted.

The split moments are related to each other by the moments of the reflection operator [5]

$$u_0^-(z, t) = R_0(z, t) * u_0^+(z, t), \quad (9)$$

$$u_2^-(z, t) = R_2(z, t) * u_0^+(z, t) + R_0(z, t) * u_2^+(z, t), \quad (10)$$

where  $R_0$  and  $R_2$  are the zeroth and second moments of the reflection operator, respectively. In the definitions (9) and (10) the following shorthand notation for a time convolution integral has been used

$$f(z, t) * g(z, t) = \int_0^t f(z, t - t')g(z, t')dt'. \quad (11)$$

Note that  $R_0(0, t)$  and  $R_2(0, t)$  are measurable quantities which later will be used as the input for a simultaneous reconstruction.

The dynamic equation for the split moments is

$$\partial_z \begin{bmatrix} u_0^+ \\ u_0^- \\ u_2^+ \\ u_2^- \end{bmatrix} = \begin{bmatrix} \alpha & \beta & 0 & 0 \\ \gamma & \delta & 0 & 0 \\ p_{11} & p_{12} & \alpha & \beta \\ p_{21} & p_{22} & \gamma & \delta \end{bmatrix} \begin{bmatrix} u_0^+ \\ u_0^- \\ u_2^+ \\ u_2^- \end{bmatrix}, \quad (12)$$

where

$$\left\{ \begin{array}{l} \alpha = -\frac{1}{c} \frac{\partial}{\partial t} - \frac{1}{2}bc + \frac{c_z}{2c}, \\ \beta = -\frac{1}{2}bc - \frac{c_z}{2c}, \\ \gamma = \frac{1}{2}bc - \frac{c_z}{2c}, \\ \delta = \frac{1}{c} \frac{\partial}{\partial t} + \frac{1}{2}bc + \frac{c_z}{2c}, \\ p_{11} = 2c\partial_t^{-1} - bc^3\partial_t^{-2} + 2cc_z\partial_t^{-2}, \\ p_{12} = -bc^3\partial_t^{-2} - 2cc_z\partial_t^{-2}, \\ p_{21} = bc^3\partial_t^{-2} - 2cc_z\partial_t^{-2}, \\ p_{22} = -2c\partial_t^{-1} + bc^3\partial_t^{-2} + 2cc_z\partial_t^{-2}, \end{array} \right. \quad (13)$$

where one sees that the split second moments  $u_2^\pm$  are not involved in the dynamic equation for split zeroth moments  $u_0^\pm$  but the split zeroth moments  $u_0^\pm$  are involved in the dynamic equation for split second moments  $u_2^\pm$ . Consequently,  $R_2$  will not appear in the PDE for  $R_0$  but  $R_0$  will appear in the PDE for  $R_2$ .

Using the dynamic equation for the split moments, we obtain the following imbedding equations

$$R_{0z} = \frac{2}{c}R_{0t} + bcR_0 + \frac{1}{2}(bc + \frac{c_z}{c})R_0 * R_0, \quad (14)$$

$$\begin{aligned} R_{2z} = & \frac{2}{c}R_{2t} + (bc^2 - 2c_z)ct + 2c(bc^2t - 2) * R_0 \\ & + (bc^2 + 2c_z)ct * R_0 * R_0 + bcR_2 + (bc + \frac{c_z}{c})R_0 * R_2 \end{aligned} \quad (15)$$

(note that the PDE for  $R_0$  is non-linear in  $R_0$ , while the PDE for  $R_2$  is linear in  $R_2$  but coupled with  $R_0$ ), and the initial conditions

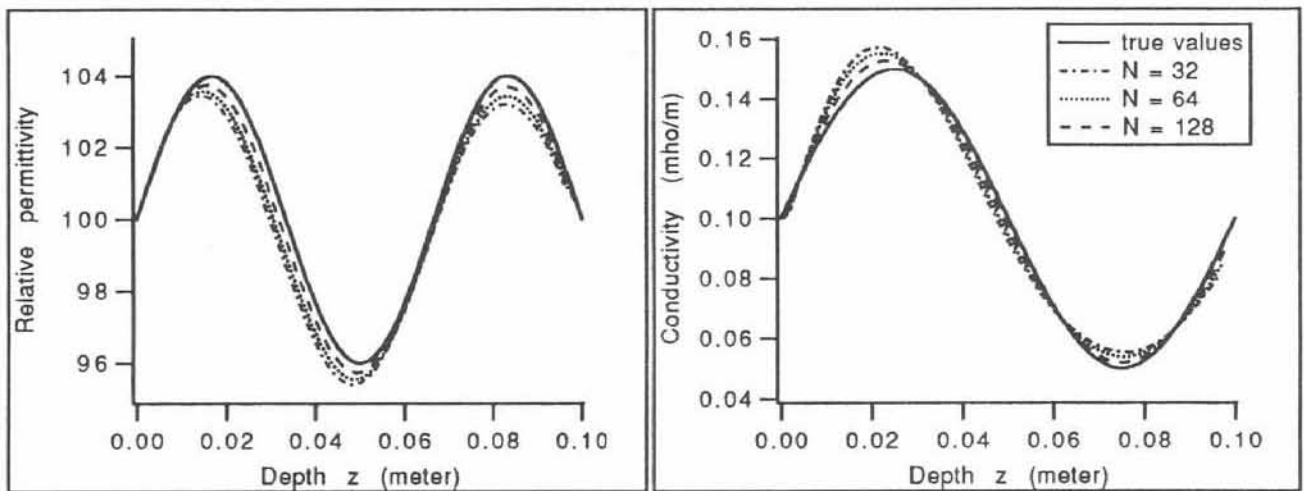
$$R_0(z, 0) = \frac{1}{4}(c_z - bc^2), \quad (16)$$

$$\ddot{R}_2(z, 0) = \frac{1}{2}c^2(3c_z - 2bc^2), \quad (17)$$

where  $\ddot{R}_2$  denotes the second time derivative of  $R_2$ .

In the inverse algorithm, we propagate the measurable boundary values  $R_0(0, t)$  and  $R_2(0, t)$  to the initial values using the PDEs for  $R_0(z, t)$  and  $R_2(z, t)$ , respectively. The

phase velocity  $c(z)$  and dissipation coefficient  $b(z)$  are then simultaneously reconstructed by the initial conditions (16) and (17). The numerical results for a simultaneous reconstruction using different data points number  $N$  are presented in the figures given below. In this numerical example we have considered the case of electromagnetic wave propagation, where  $c(z) = 1/\sqrt{\epsilon(z)\mu_0}$ ,  $b(z) = \mu_0\sigma(z)$  ( $\epsilon$  is the permittivity,  $\sigma$  is the conductivity and  $\mu_0$  is the permeability in vacuum).



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